

University of California
Berkeley

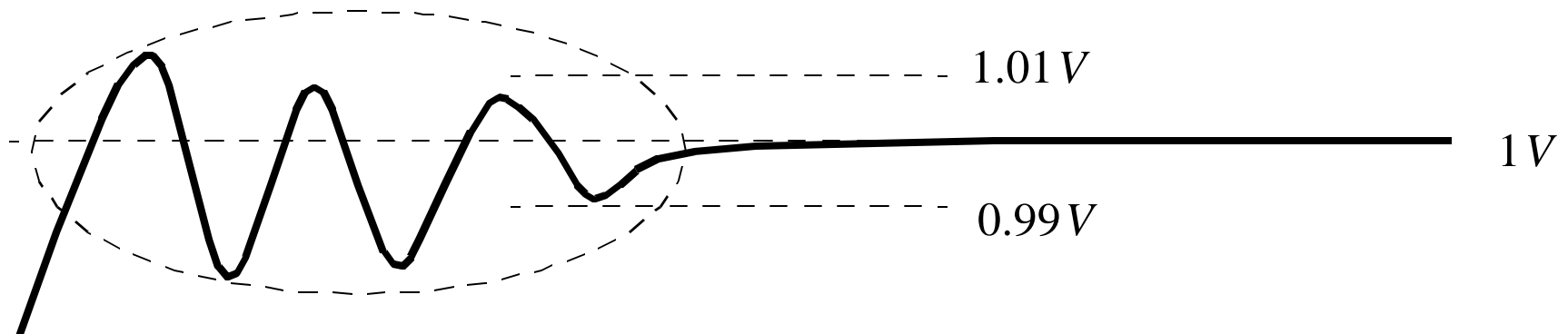
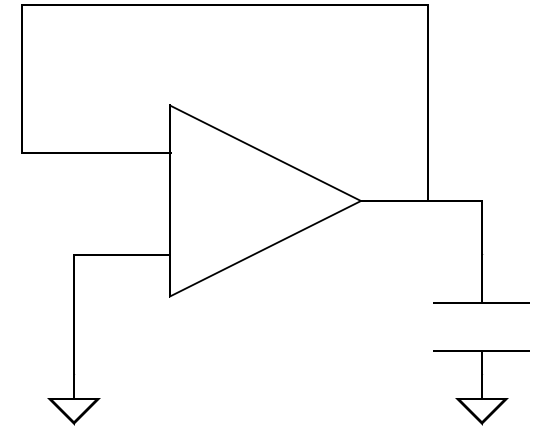
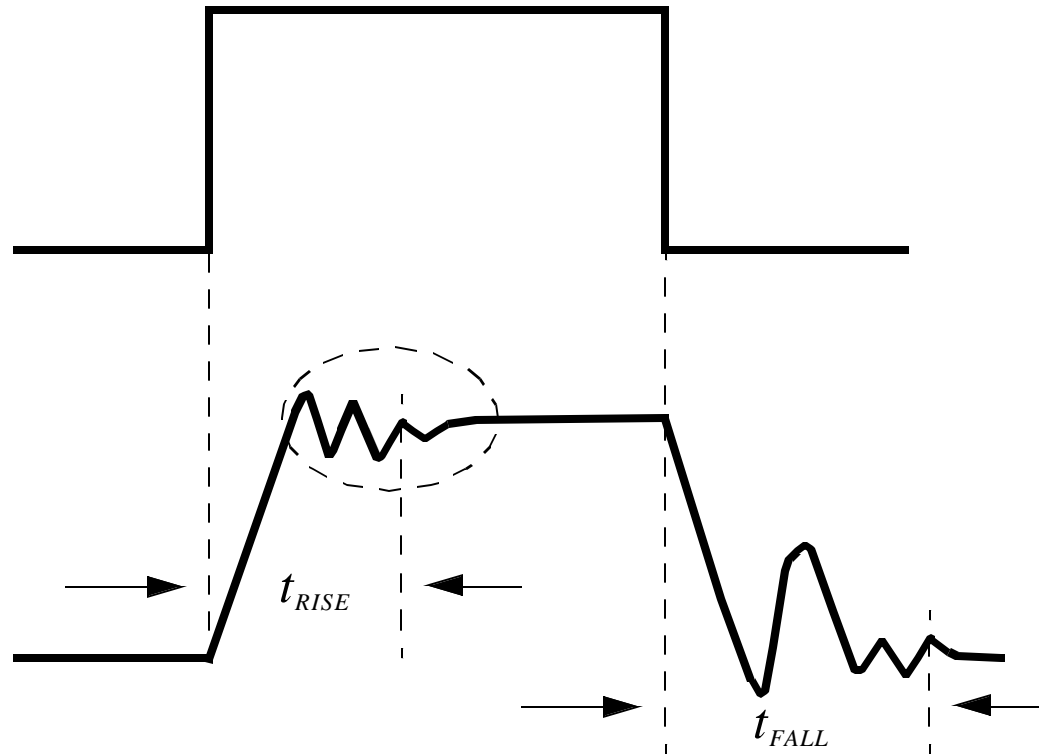
College of Engineering
Department of Electrical Engineering
and Computer Science

Robert W. Brodersen
EECS140

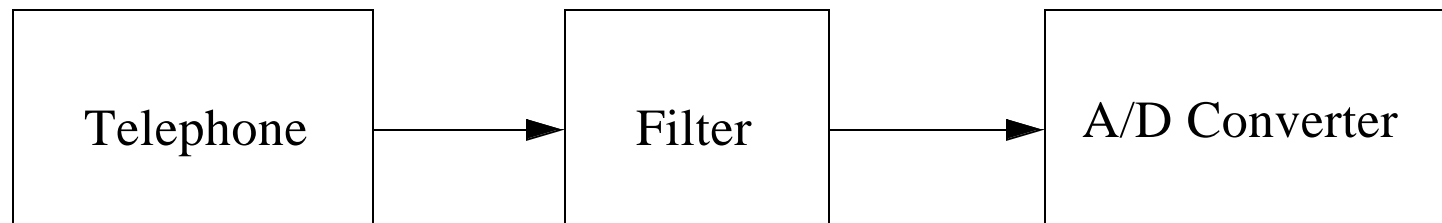
Analog Circuit Design

Lectures
on
APPLICATIONS

APP-01

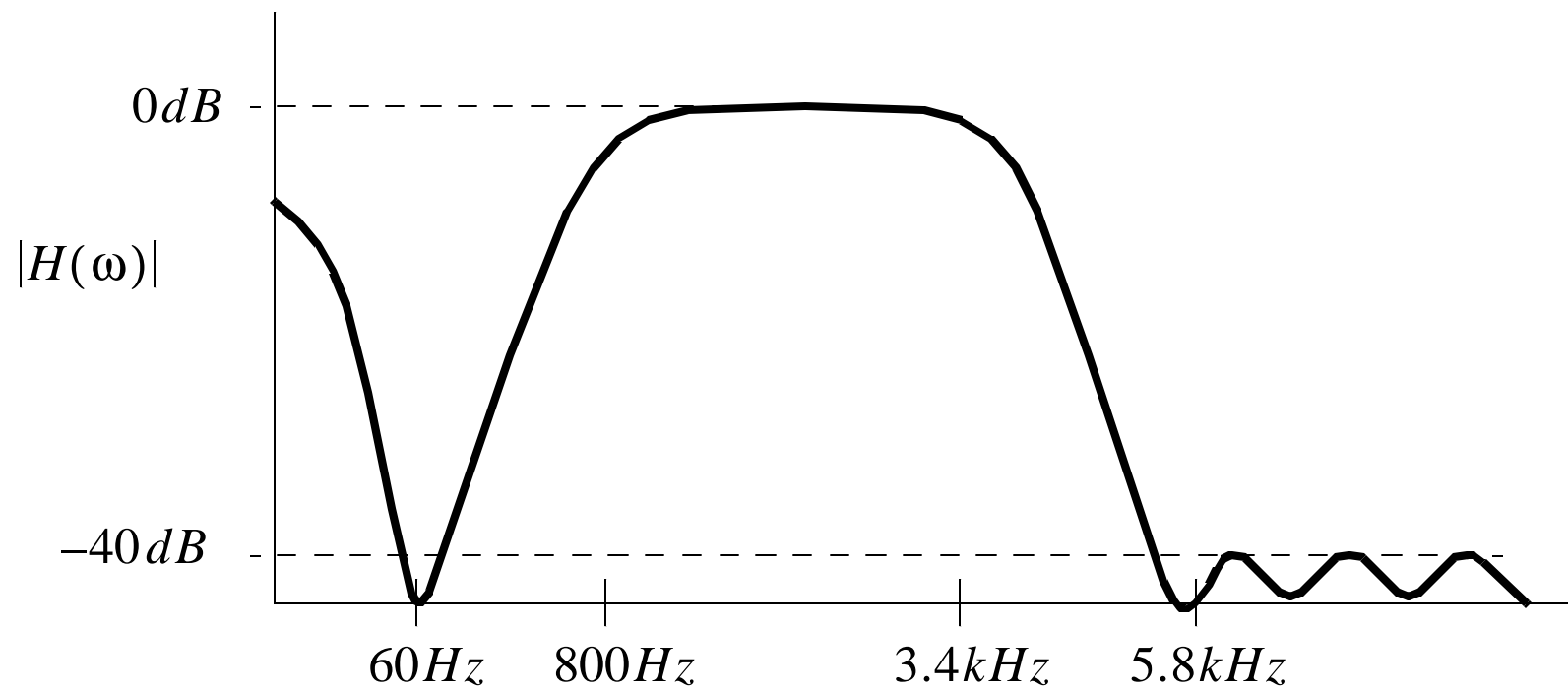


15-20 Years Ago



PCM Codec

APP-03

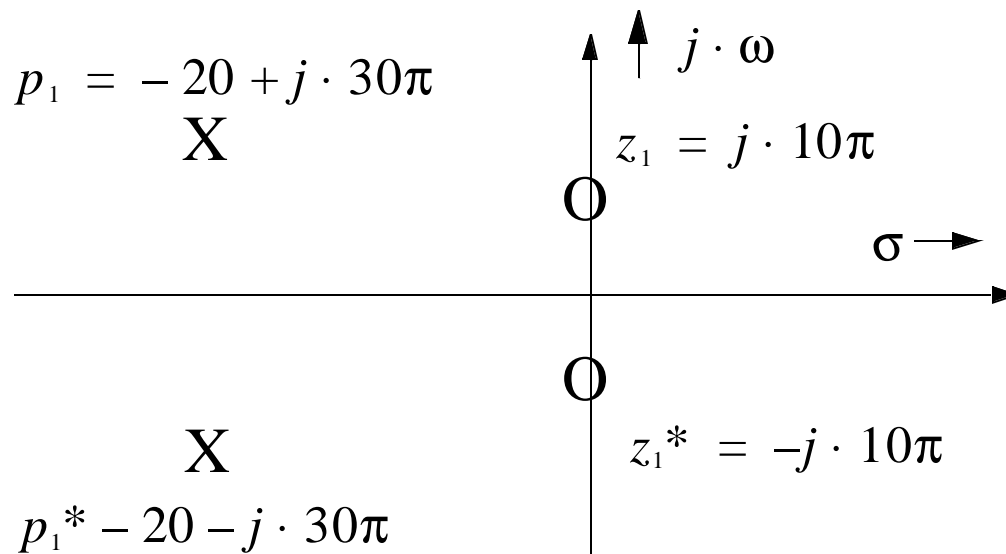


Pole - Zero Diagrams

APP-04

A convenient way of visualizing transfer functions,
the Laplace Transform :

$$H_{(s)} = \frac{V_{OUT}(s)}{V_{IN}(s)} = \frac{(s - z_1) \cdot (s - z_1^*)}{(s - p_1) \cdot (s - p_1^*)}$$



S - PLANE
 $S = \sigma + j \cdot \omega$

Poles - Zero Diagrams (Cont.)

APP-05

Often what we are really interested in is $|H(\omega)|$, i.e. the magnitude and phase at frequency, ω .

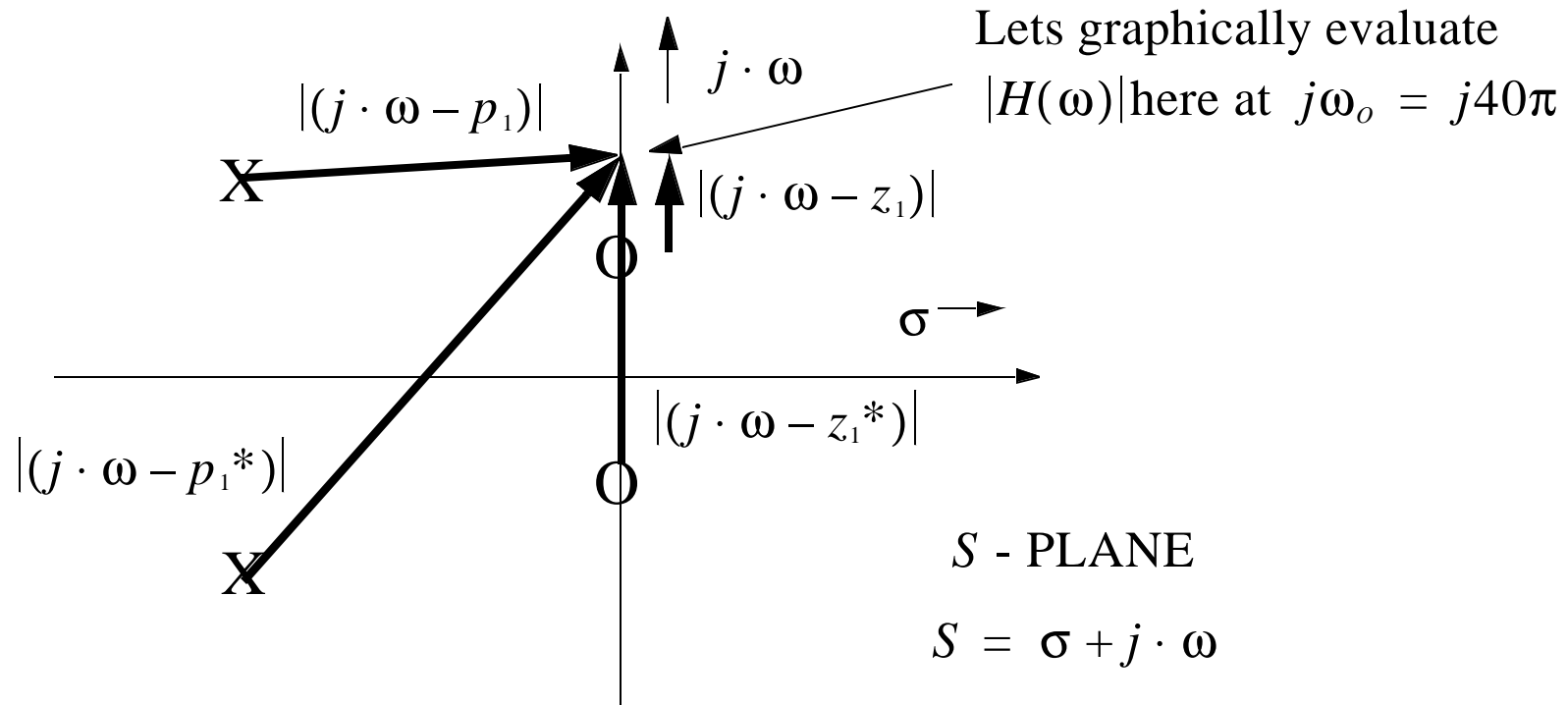
$$H(\omega) = H(s)|_{s=j\cdot\omega}$$

$$H(\omega) = \frac{(j\cdot\omega - z_1) \cdot (j\cdot\omega - z_1^*)}{(j\cdot\omega - p_1) \cdot (j\cdot\omega - p_1^*)}$$

To find the magnitude use the fact that magnitude of the products equals the product of the magnitudes, so that :

$$|H(\omega)| = \left| \frac{(j\cdot\omega - z_1) \cdot (j\cdot\omega - z_1^*)}{(j\cdot\omega - p_1) \cdot (j\cdot\omega - p_1^*)} \right| = \frac{|(j\cdot\omega - z_1)| \cdot |(j\cdot\omega - z_1^*)|}{|(j\cdot\omega - p_1)| \cdot |(j\cdot\omega - p_1^*)|}$$

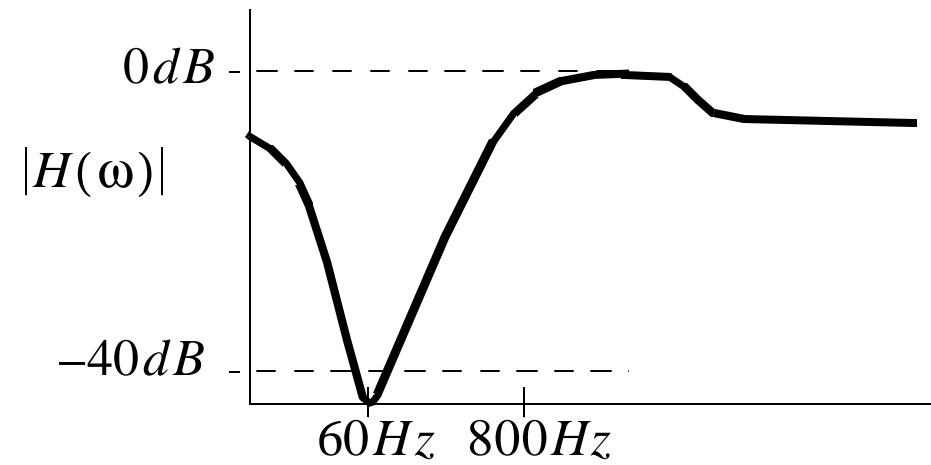
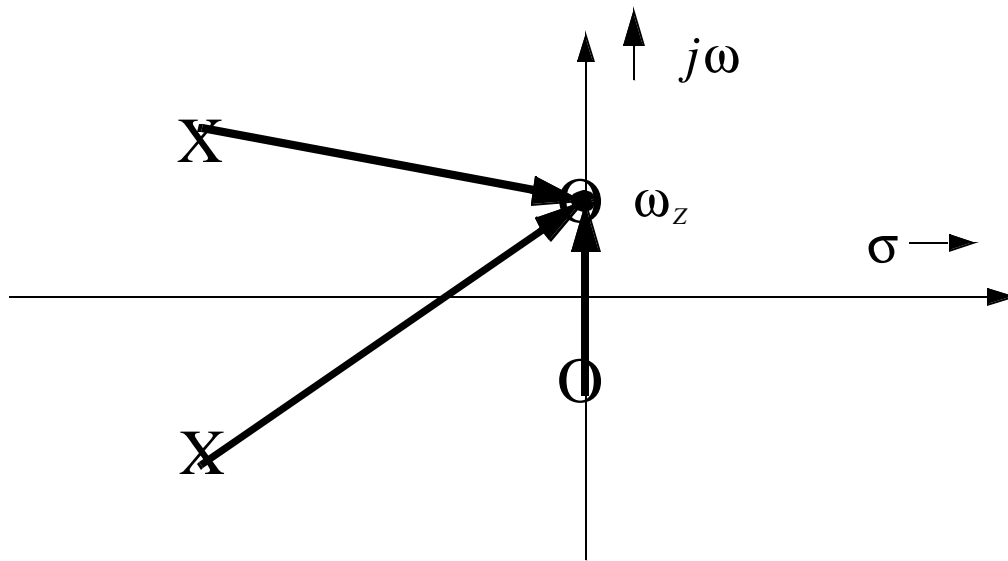
Poles - Zero Diagrams (Cont.)



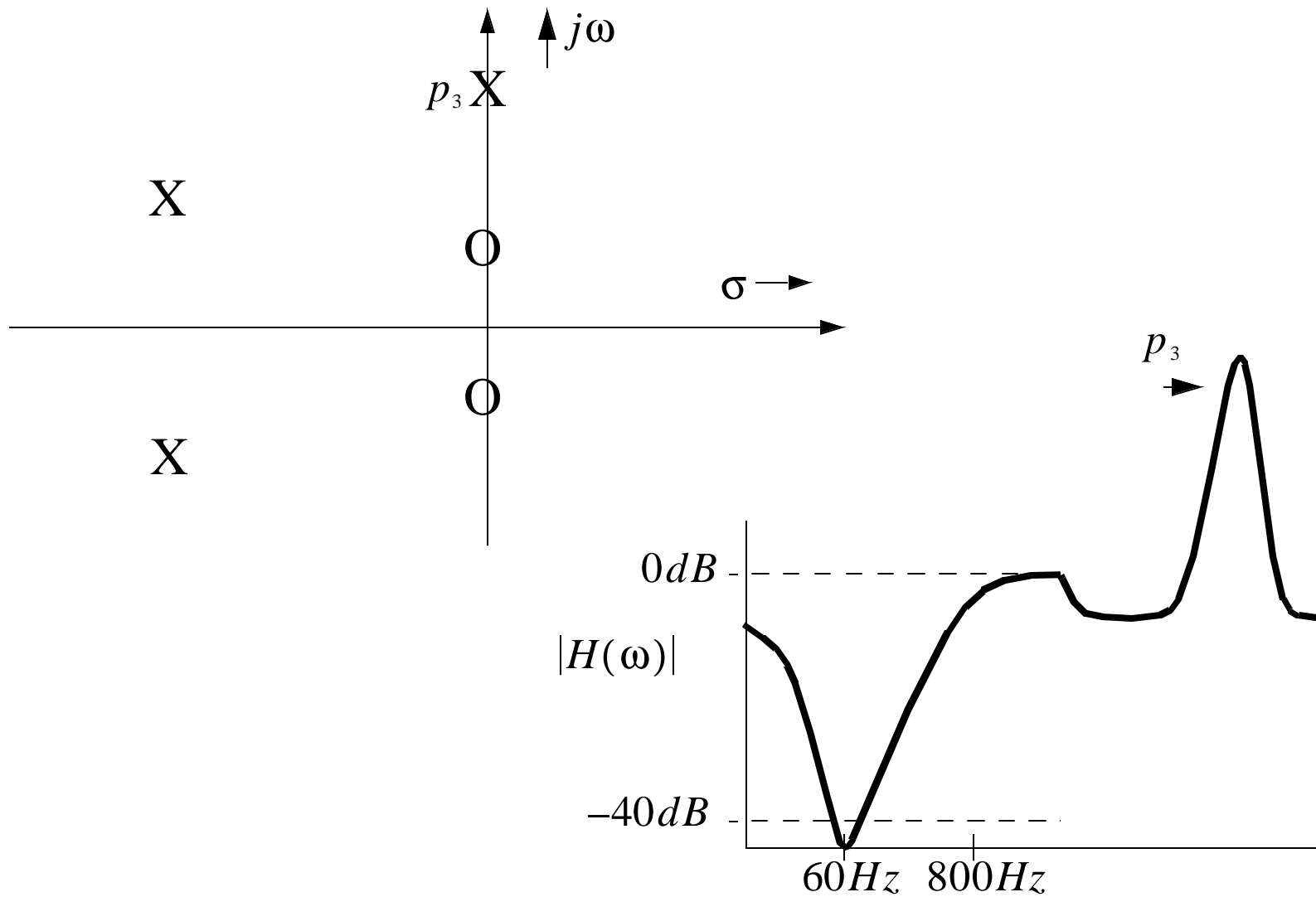
The magnitude $|H(\omega)|$ is the product of the lengths of vectors 3 & 4 divided by the product of the lengths of vectors 1 & 2.

Poles - Zero Diagrams (Cont.)

APP-07

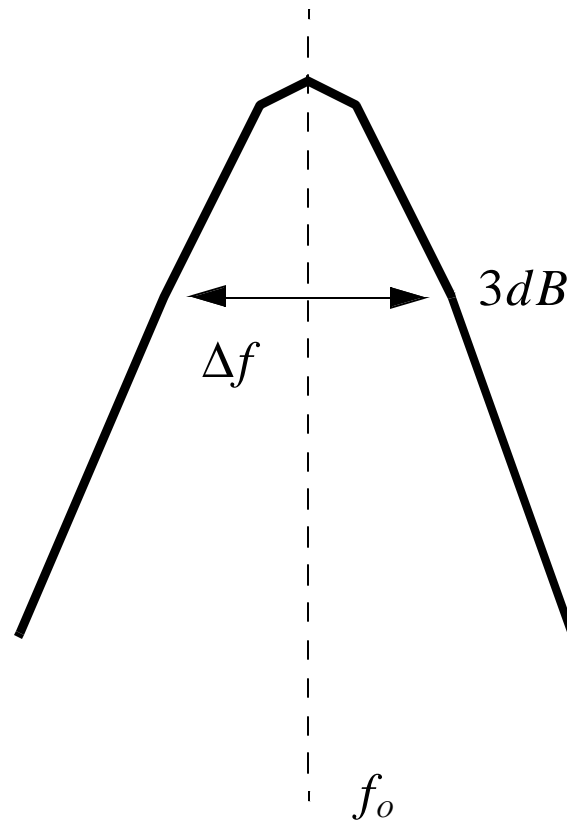


Poles - Zero Diagrams (Cont.)



Poles - Zero Diagrams (Cont.)

APP-09

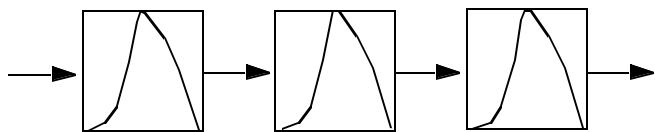
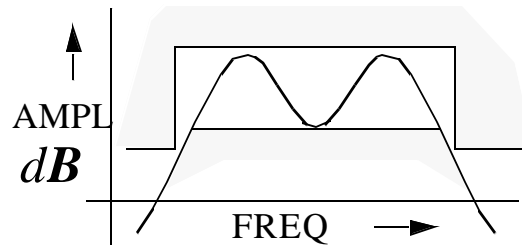


$$Q = \frac{f_o}{\Delta f}$$

Filter Design

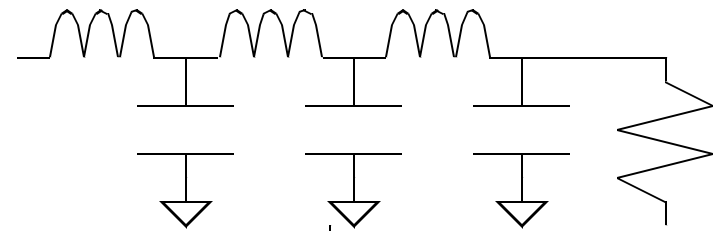
APP-10

Specification

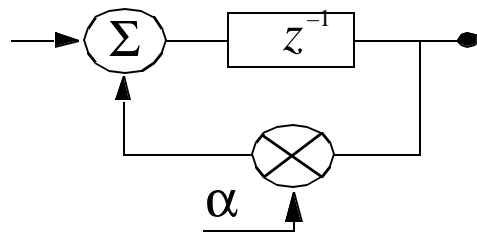


Continuous Time Factorization into 2-Pole,2-Zero sections (Biquadratic)

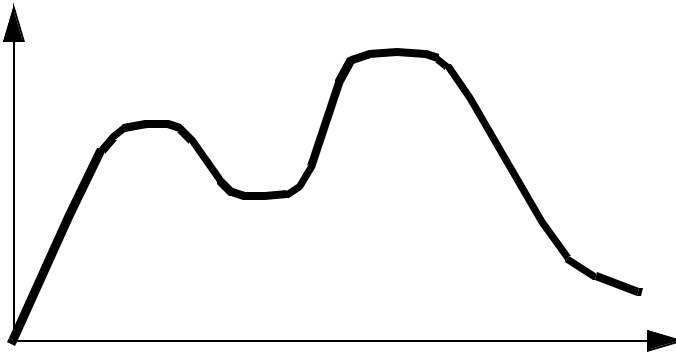
LC Prototypes



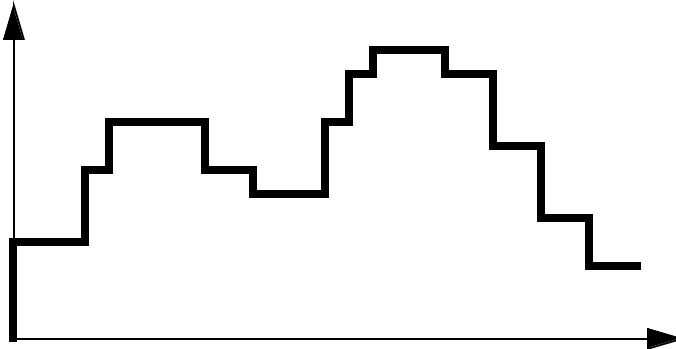
Chose an "Equivalent" discrete time structure.
 Use appropriate cont. \rightarrow Discrete Transformation (i.e. Bilinear, Mapping differentials)



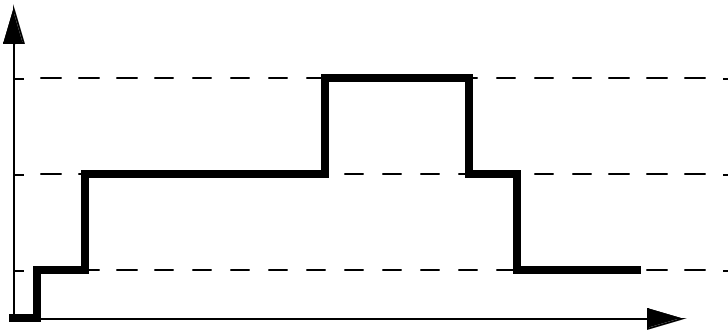
Simulate Discrete Time implementation and compare with original spec.(DINAP)



Active RC Filter
(Continuous Time)

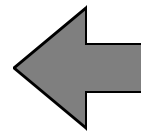
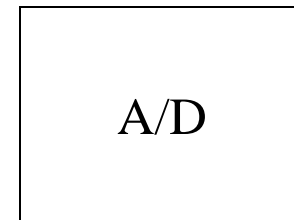
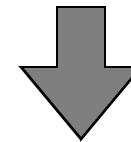
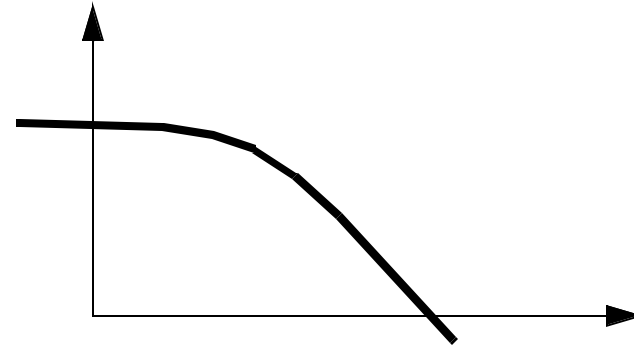
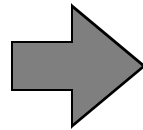
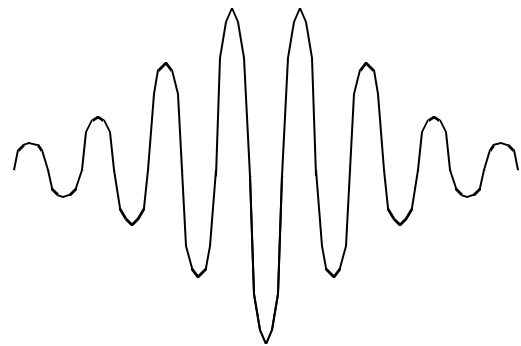


Switched Capacitor Circuits
(Sampled Data any Amplitude)



Digital Filter
(Sampled Data, Quantized Amplitude)

APP-12

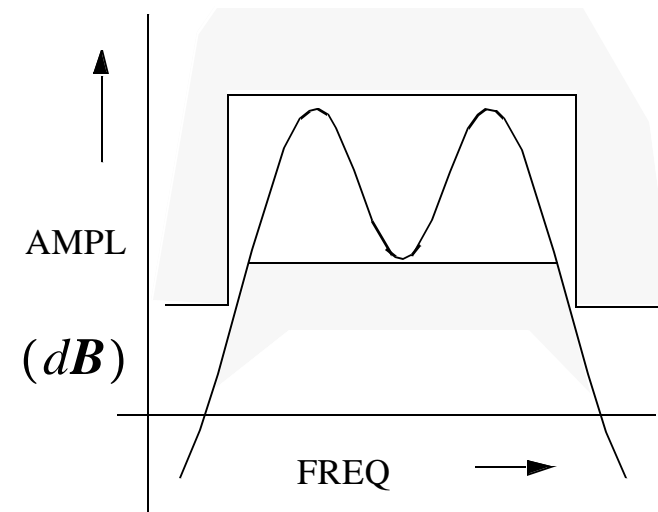


Typical Filter Specifications

APP-13

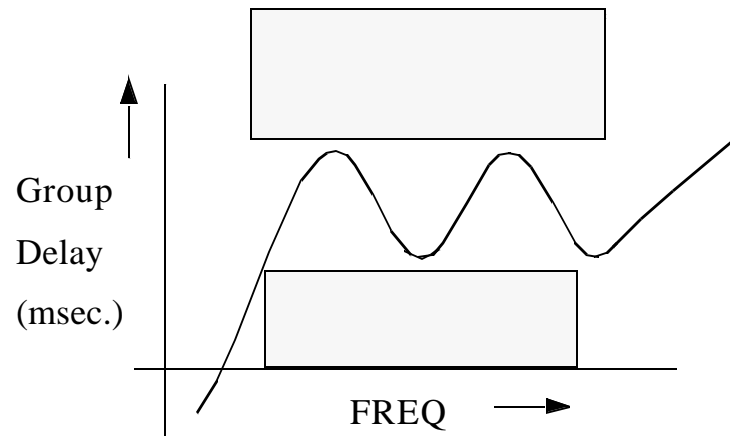
Continuous time specifications
of transfer function $|H(\omega)|$

$$\frac{V_{OUT}(\omega)}{V_{IN}(\omega)} = H(\omega) = |H(\omega)| \cdot e^{j \cdot \theta(\omega)}$$



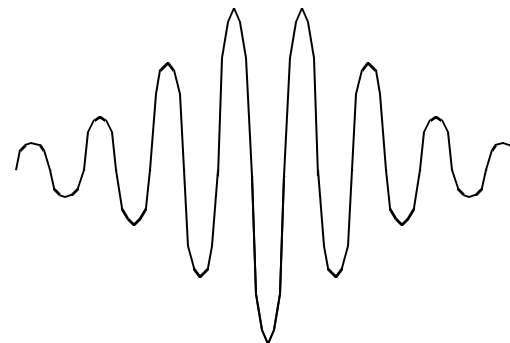
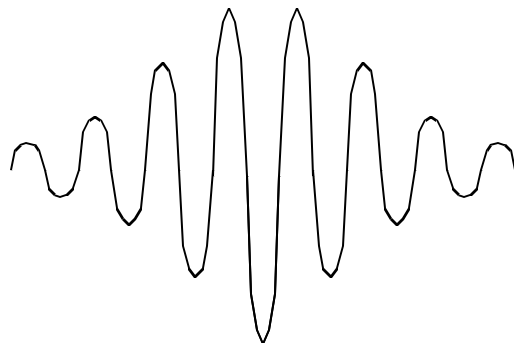
$$\text{Amplitude (Magnitude in dB)} = 10 \log \left[\underbrace{H(\omega) \cdot H^*(\omega)}_{|H(\omega)|^2} \right]$$

Typical Filter Specifications (Cont.)



$$\text{Group Delay} = \frac{\partial}{\partial \omega} \theta(\omega)$$

← Group Delay →

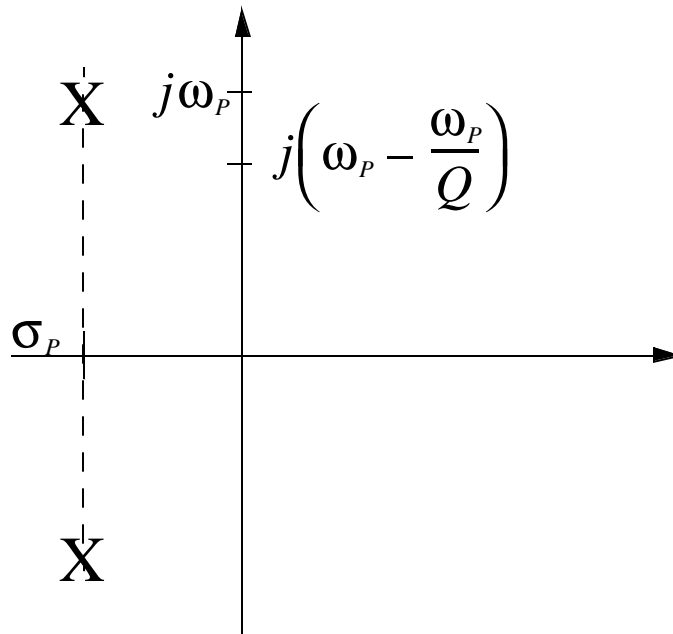


Types of 2-Pole Transfer Functions

APP-15

Lowpass :

$$H(s) = \frac{\omega_o^2}{s^2 + \frac{\omega_o}{Q} \cdot s + \omega_o^2}$$

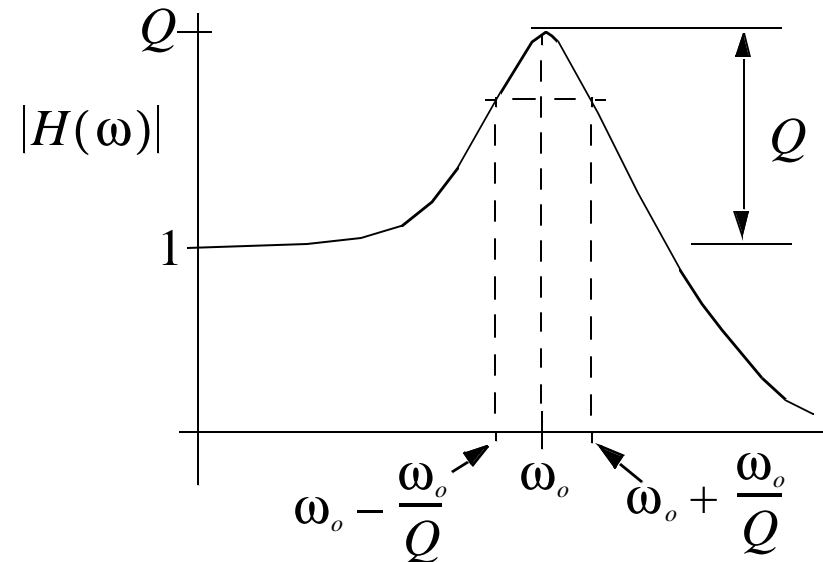


$$s_1, s_1^* = -\frac{\omega_o}{Q} \mp \sqrt{\left(\frac{\omega_o}{Q}\right)^2 - 4 \cdot \omega_o^2}$$

Types of 2-Pole Transfer Functions (Cont.)

APP-16

(Lowpass)



$$\omega_o \equiv |s_p| = \sqrt{s_p^2 + \omega_p^2}$$

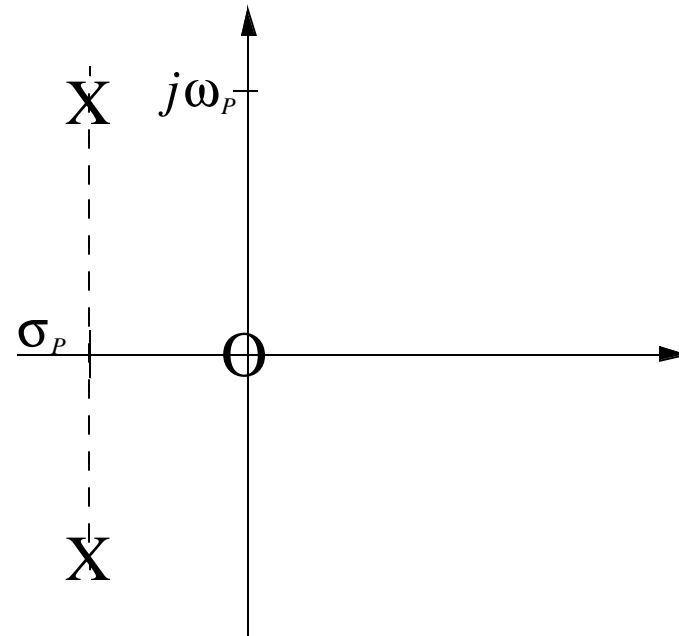
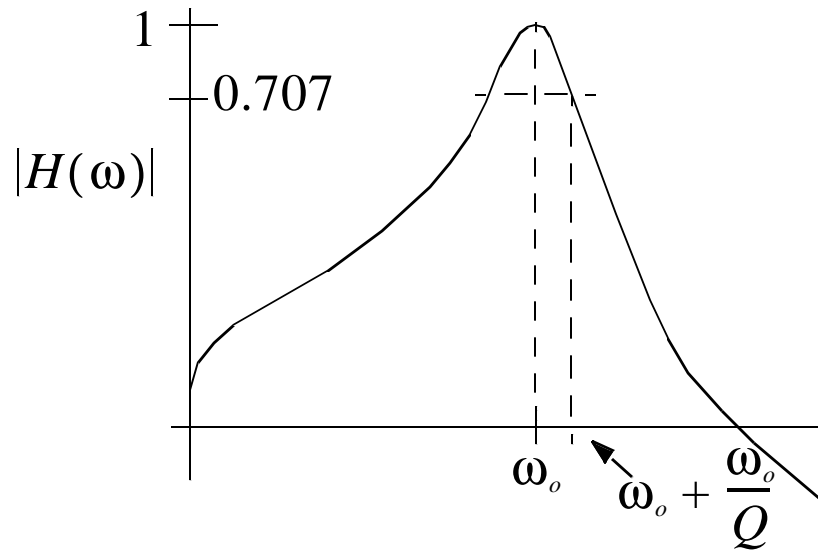
$$Q \equiv \frac{|s_p|}{2 \cdot |s_p|} = \frac{1}{2} \cdot \sqrt{1 + \left(\frac{\omega_p}{s_p}\right)^2}$$

Types of 2-Pole Transfer Functions (Cont.)

APP-17

Bandpass :

$$H(s) = \frac{\frac{\omega_o}{Q} \cdot s}{s^2 + \frac{\omega_o}{Q} \cdot s + \omega_o^2}$$



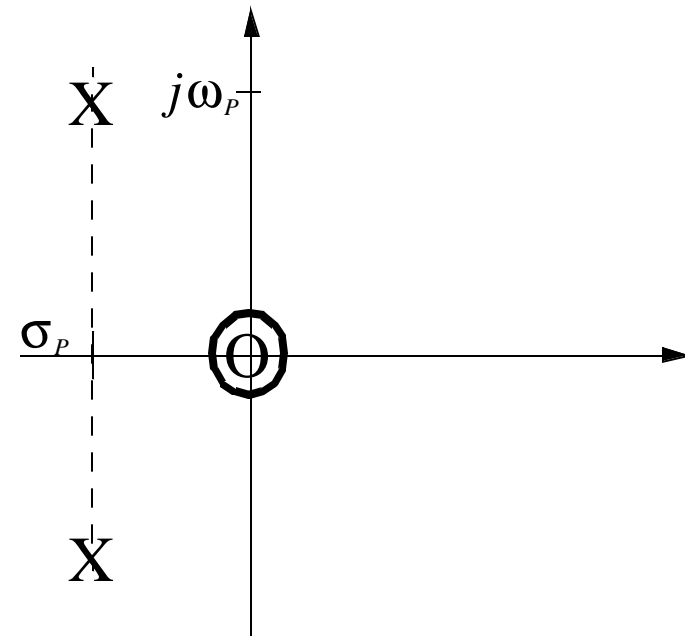
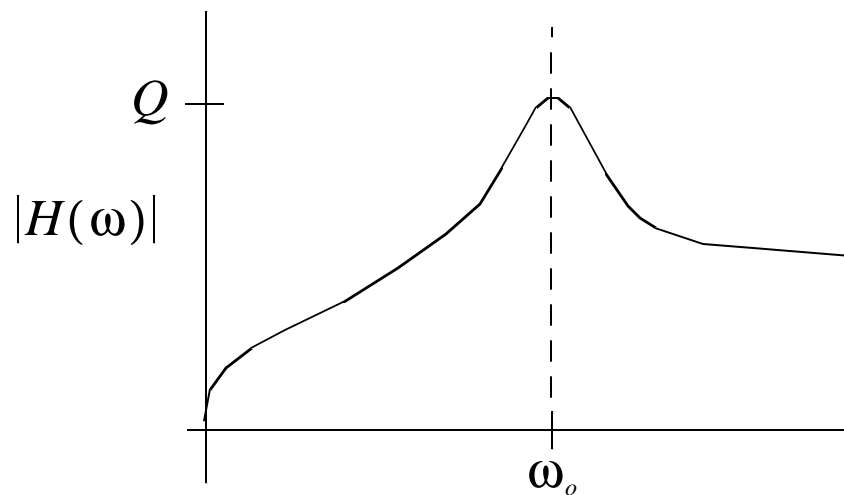
Types of 2-Pole Transfer Functions (Cont.)

APP-18

Highpass :

Highpass = 1 - (*Lowpass*) - (*Bandpass*)

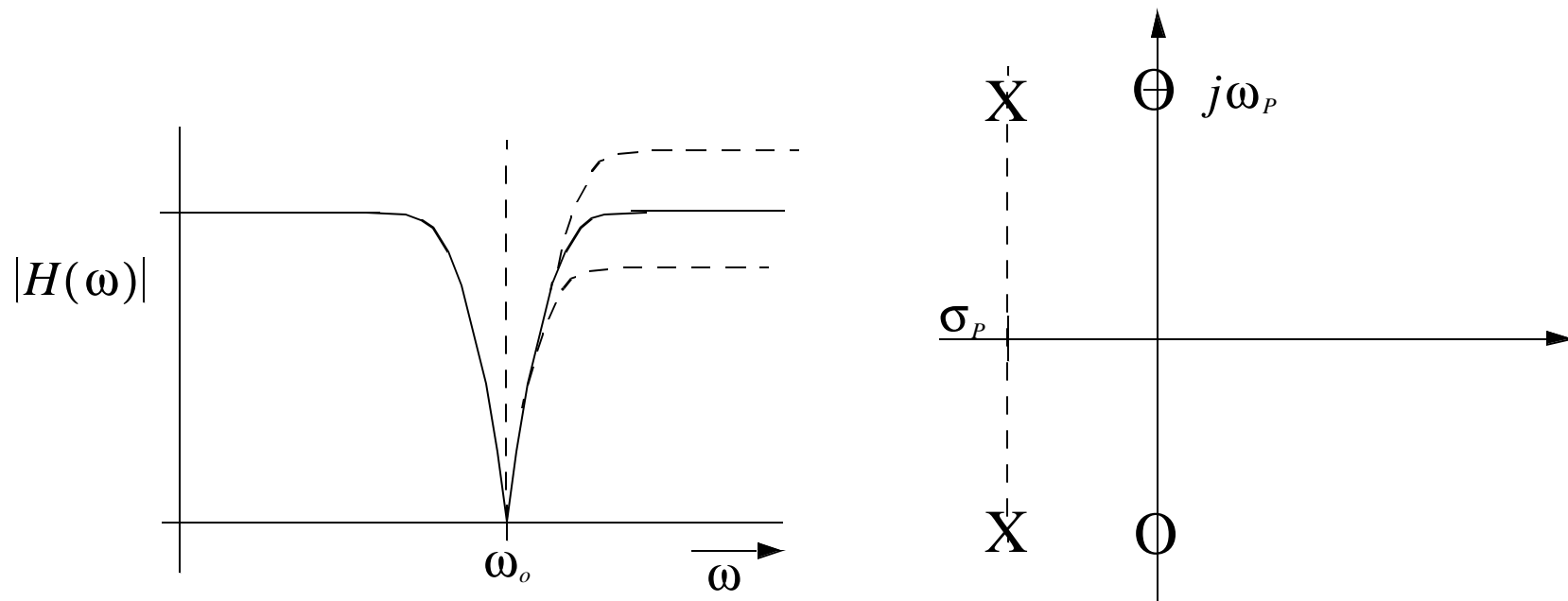
$$= 1 - \left(\frac{\frac{1}{\omega_o^2} + \frac{\omega_o \cdot s}{Q}}{s^2 + \frac{\omega_o}{Q} \cdot s + \omega_o^2} \right) = \frac{s^2}{s^2 + \frac{\omega_o}{Q} \cdot s + \omega_o^2}$$



Types of 2-Pole Transfer Functions (Cont.)

Bandstop (or Notch) :

$$\text{Bandstop} = 1 - \frac{s \cdot \left(\frac{\omega_o}{Q}\right)}{s^2 + \frac{\omega_o}{Q} \cdot s + \omega_o^2} = \frac{s^2 + \omega_o^2}{s^2 + \frac{\omega_o}{Q} \cdot s + \omega_o^2}$$

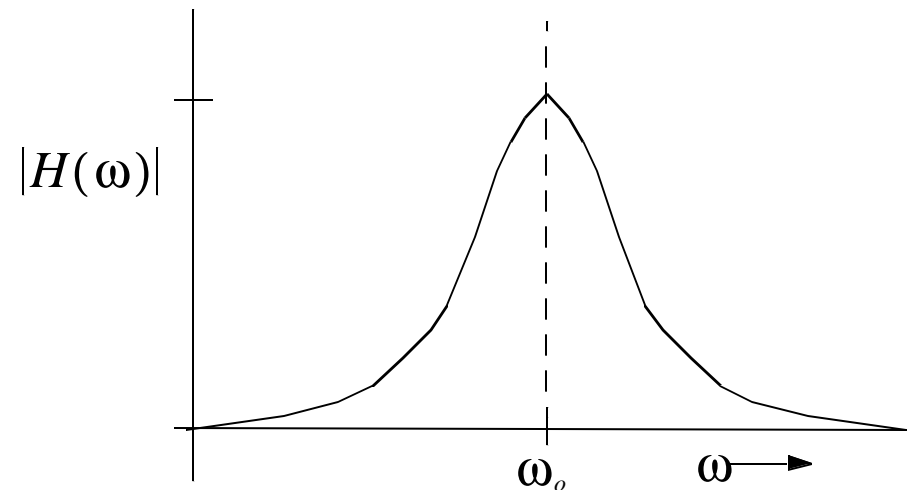
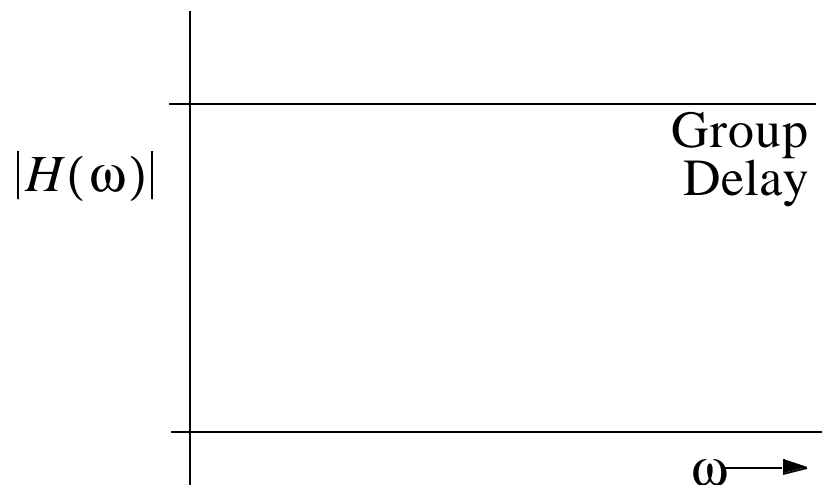
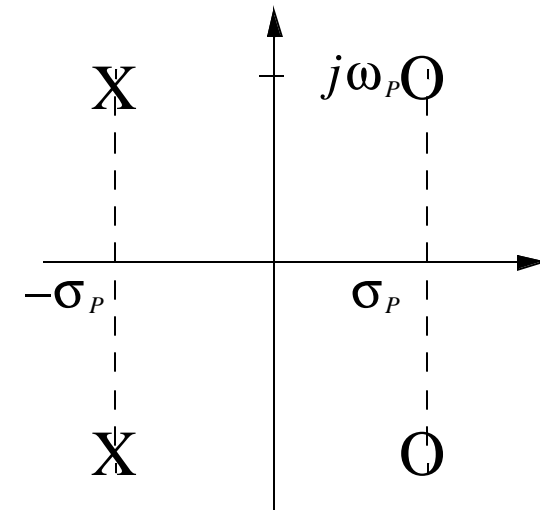


Types of 2-Pole Transfer Functions (Cont.)

All Pass (Delay Equalizer) :

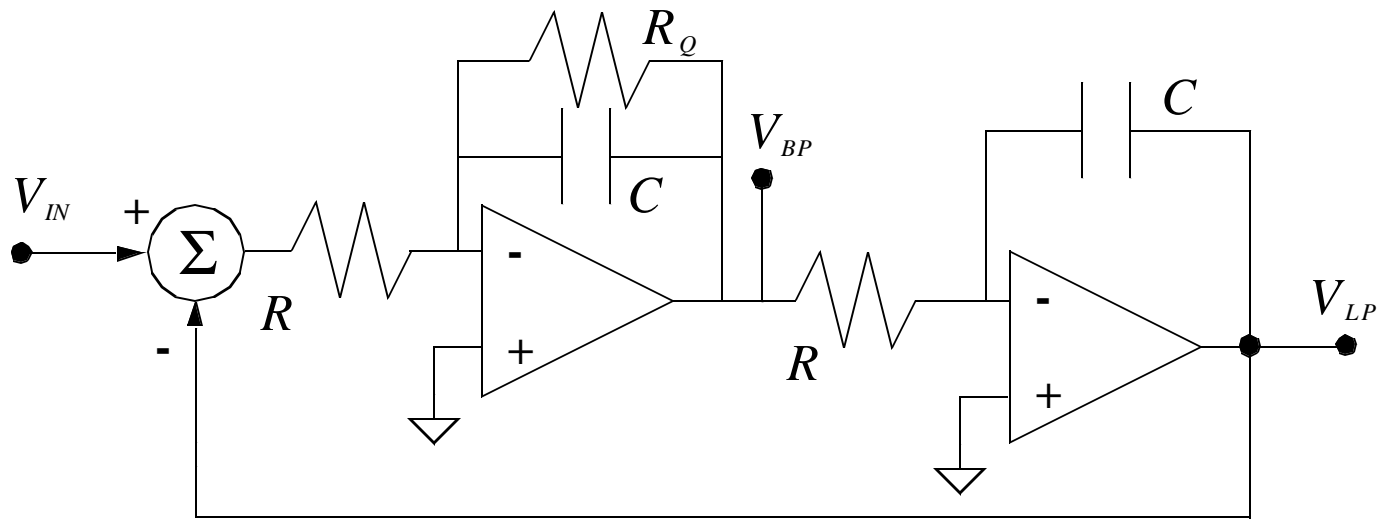
= 1 - 2 - (Bandpass)

$$H(s) = 1 - \frac{2 \cdot s \cdot \frac{\omega_o}{Q}}{s^2 + \frac{\omega_o}{Q} \cdot s + \omega_o^2} = \frac{s^2 - \frac{\omega_o}{Q} \cdot s + \omega_o^2}{s^2 + \frac{\omega_o}{Q} \cdot s + \omega_o^2}$$



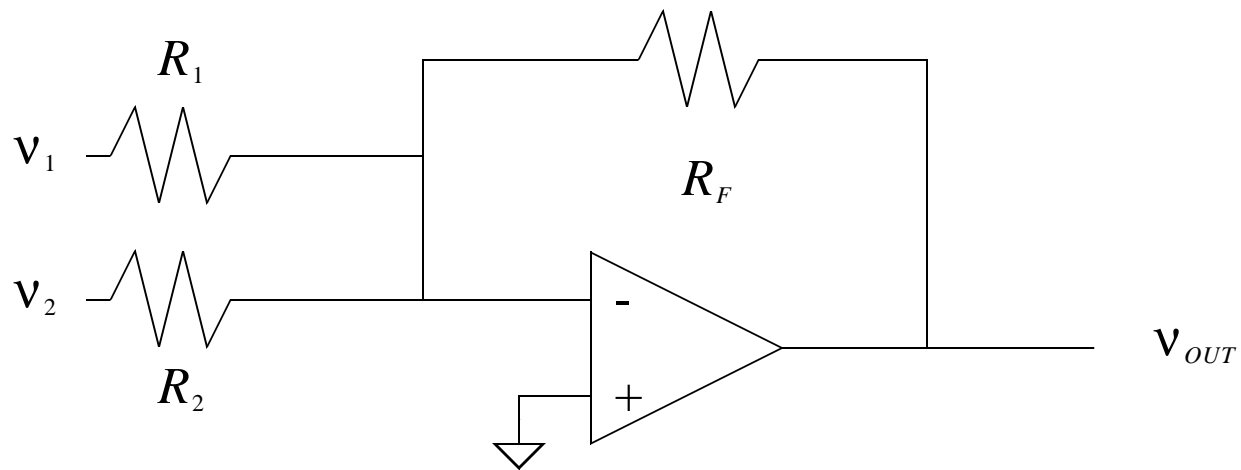
State Variable Active RC Filter

Lowpass & Bandpass :



State Variable Active RC Filter (Cont.)

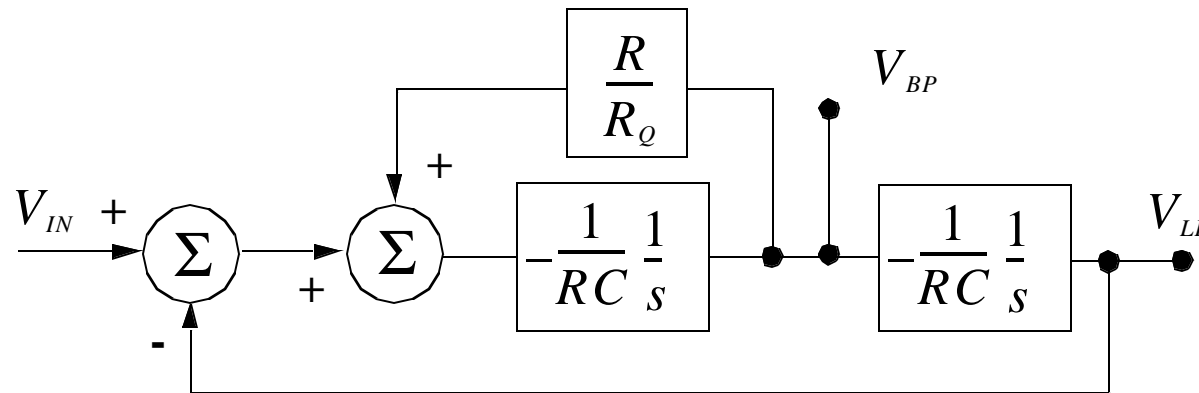
APP-22



$$v_{OUT} = v_1 \frac{R_F}{R_1} + v_2 \frac{R_F}{R_2}$$

State Variable Active RC Filter (Cont.)

APP-23



$$\frac{V_{LP}}{V_{IN}} = \frac{\left(\frac{1}{RC}\right)^2}{s^2 + \left(\frac{1}{R_C \cdot C} \cdot s\right) + \frac{1}{R_C}} = \frac{\omega_o^2}{s^2 + \frac{\omega_o}{Q}s + \omega_o^2}$$

$$\therefore \omega_o = \frac{1}{RC} \qquad Q = \frac{R_Q}{R}$$

State Variable Active RC Filter (Cont.)

APP-24

$$\frac{V_{BP}}{V_{IN}} = \frac{-\frac{1}{RC} \cdot S}{S + \frac{1}{R_c \cdot C} \cdot S + \left(\frac{1}{R_c}\right)^2} = \frac{-\omega_o \cdot S}{S + \frac{\omega_o}{Q} \cdot S + \omega_o^2}$$

(Note GAIN is $-Q$ at ω_o instead of 1
as required for a canonical bandpass.)

Highpass :

$$Highpass = 1 - (Lowpass) - (Bandpass)$$

Using a 3RD OP AMP we form the sum,

$$V_{HIGHPASS} = V_{IN} - V_{LP} + \frac{1}{Q} \cdot V_{BP}$$

State Variable Active RC Filter (Cont.)

Bandstop :

$$\text{Bandstop} = 1 - (\text{Bandpass})$$

$$V_{\text{BANDSTOP}} = V_{\text{IN}} + \frac{1}{Q} \cdot V_{\text{BP}}$$

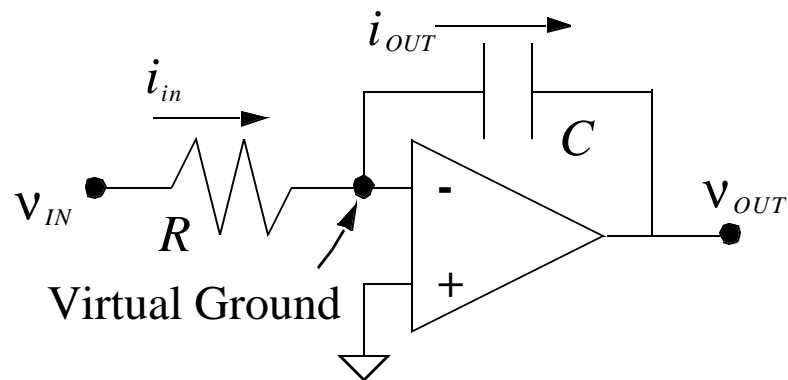
All Pass :

$$\text{Allpass} = 1 - 2(\text{Bandpass})$$

$$V_{\text{ALLPASS}} = V_{\text{IN}} + \frac{2}{Q} \cdot V_{\text{BP}}$$

Active RC Filters - Integrator or State Variable Configurations

Basic Element is the OP AMP Integrator :



Active RC Filters - Integrator or State Variable Configurations (Cont.)

$$i_{OUT} = i_{in}$$

$$i_{in} = \frac{v_{in} - 0}{R} = \frac{v_{in}}{R}$$

$$-SC \cdot v_{OUT} = \frac{v_{in}}{R}$$

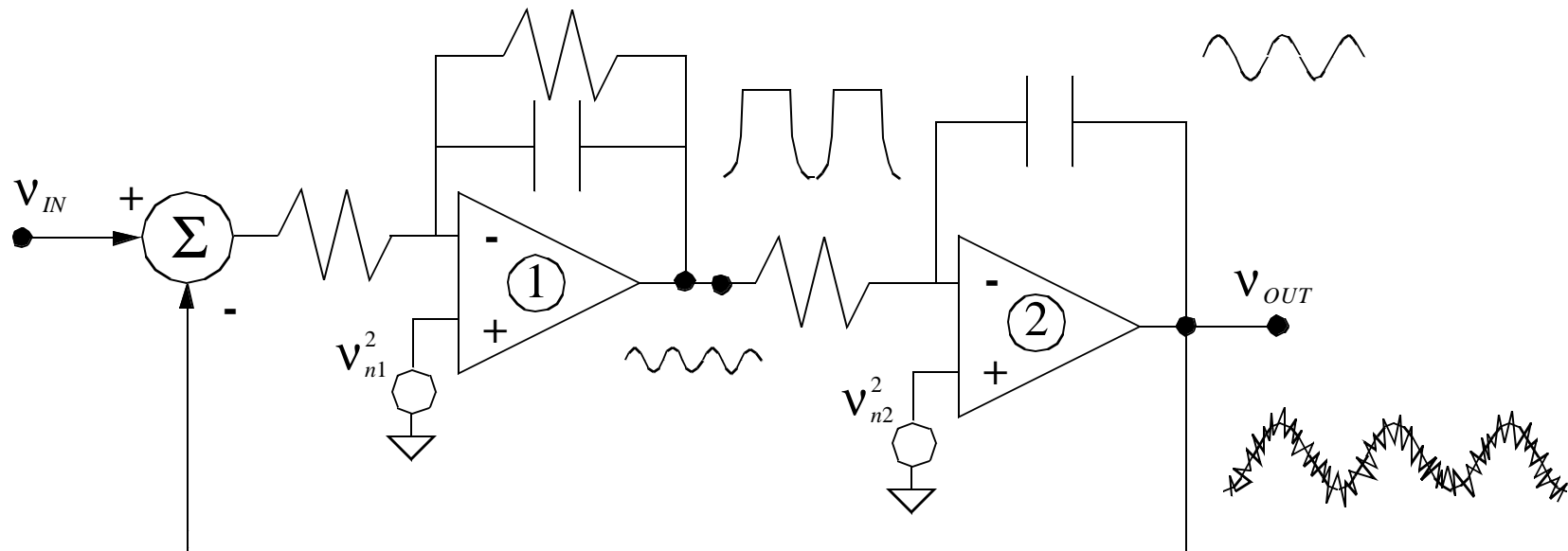
$$i_{OUT} = \frac{0 - v_{OUT}}{1/SC} = -SC \cdot v_{OUT}$$

$$\frac{v_{OUT}}{v_{in}} = -\frac{1}{RC} \cdot \frac{1}{S} = H(s)$$

$$H(s)|_{s=j\omega} = -\frac{1/RC}{j\omega}$$

Active RC Filters - Integrator or State Variable Configurations (Cont.)

Scaling of the internal node voltages for maximum dynamic range.



Active RC Filters - Integrator or State Variable Configurations (Cont.)

For maximum dynamic range. (Signal / Noise Ratio) the outputs of both op amps should have the same peak values.

If this is not true;

- If op amp #1 has a peak signal larger than #2, then #1 will saturate early limiting the maximum signal.
- If #1 has a peak amplitude less than #2, then there must be gain from #1 to #2 and the noise of #1 will be amplified.

$$f_o = 3kHz$$

$$\omega_o = \frac{20krad}{sec} = \frac{1}{RC}$$

$$C = 10pF$$

$$R = \frac{1}{10pF \cdot 20 \cdot 10^3} = \frac{1}{2 \cdot 10^{-7}}$$

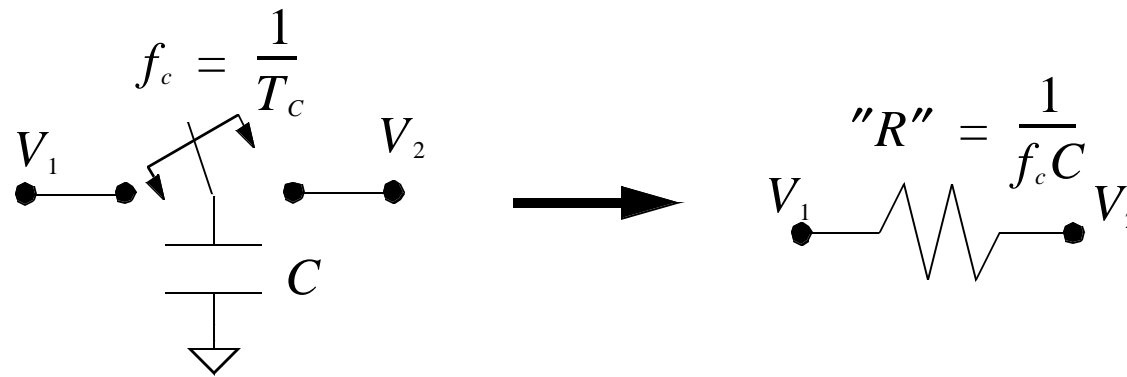
$$R = 5M\Omega$$

$$R \pm 10\% \quad C \pm 10\%$$

$$RC \pm 20\%$$

Basic Element of Switched - Capacitor Filters

APP-31



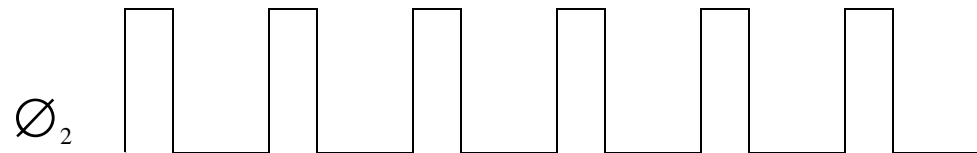
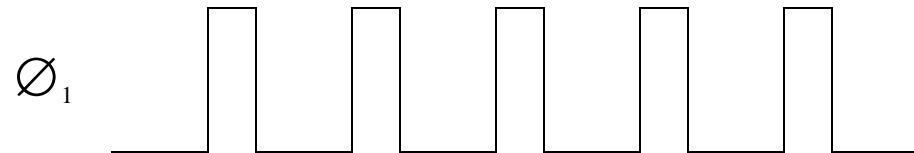
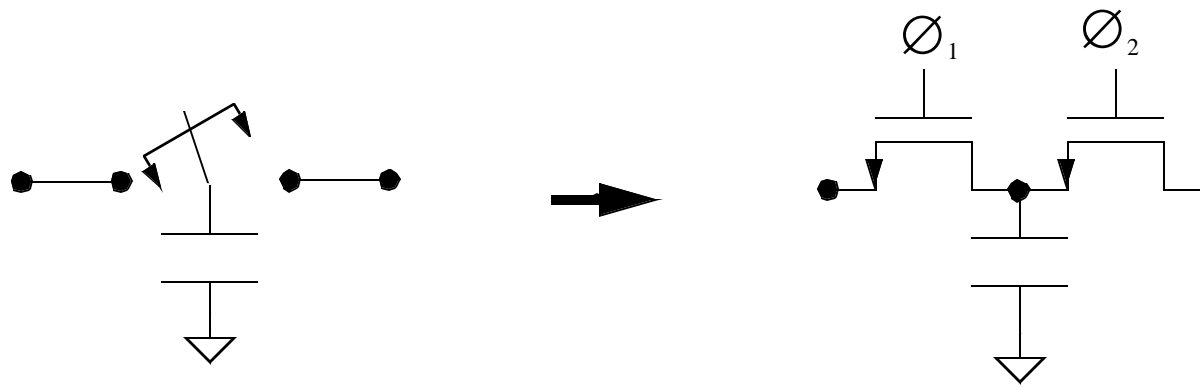
$$\Delta Q = C \cdot (V_2 - V_1)$$

$$"I" = \frac{\Delta Q}{T_c} = f_c \cdot C \cdot (V_2 - V_1)$$

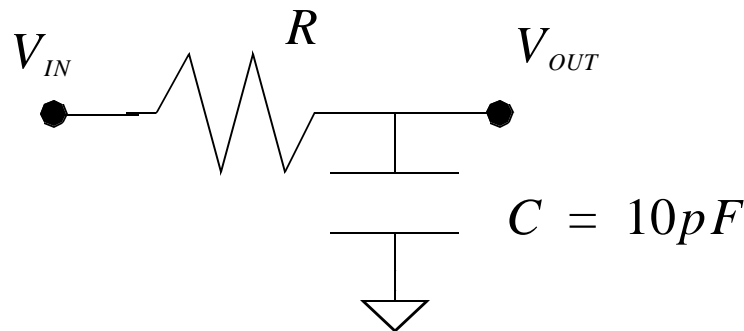
$$"R" = \frac{V_2 - V_1}{I} = \frac{1}{f_c C}$$

Basic Element of Switched - Capacitor Filters (Cont.)

APP-32



Size of Switched - Capacitor, Resistors



$$f_{3dB} = 10kHz$$

$$R = \frac{1}{2\pi \cdot f_{3dB} \cdot C} = \frac{1}{(6.28) \cdot (10^4) \cdot (10^{-11})}$$

$$= 1.6M\Omega$$

Area of S-C Resistor

$$(f_c = 100kHz)$$

$$C_R = \frac{1}{f_c \cdot R} = \frac{1}{10^5 \times 1.6 \times 10^6}$$

$$= 6.28pF$$

$$\approx 31mil^2s (@5mil^2/pF)$$

Area of Poly Resistor

$$(50\Omega/\square)$$

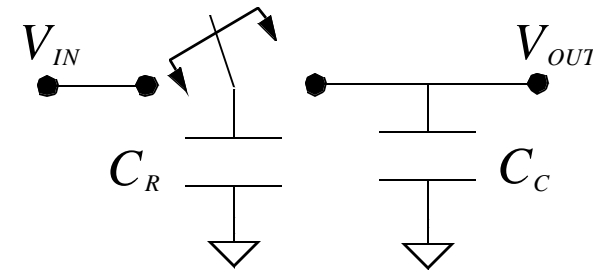
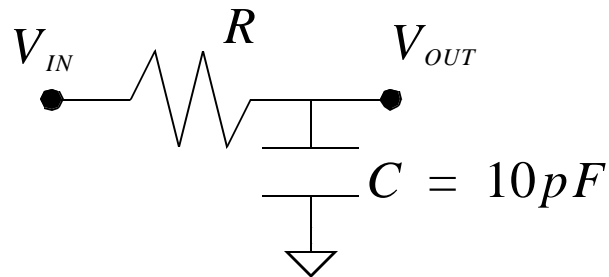
$$= 32 \times 10^3 \square$$

$$\approx 3.2 \times 10^3 mil^2s (@1mil^2/\square)$$

Equivalent S-C resistor about

2 orders of magnitude smaller in area.

Simple Filter



$$\omega_{3dB} = \frac{1}{RC}$$

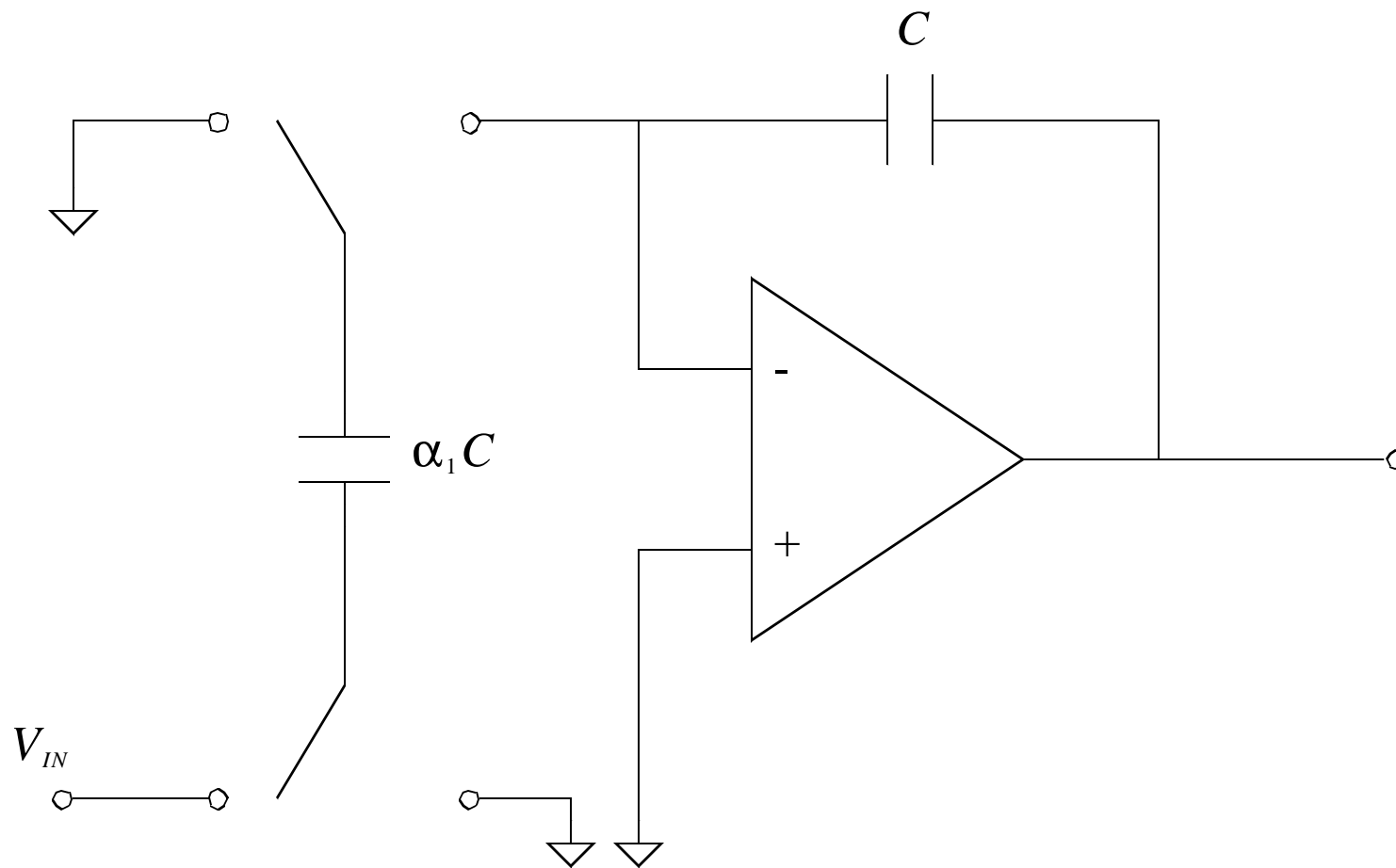
Requires absolute
control of R and C

$$\omega_{3dB} \approx \frac{1}{\left(\frac{1}{f_c \cdot C_R}\right) \cdot C_C} = f_c \cdot \left(\frac{C_R}{C_C}\right)$$

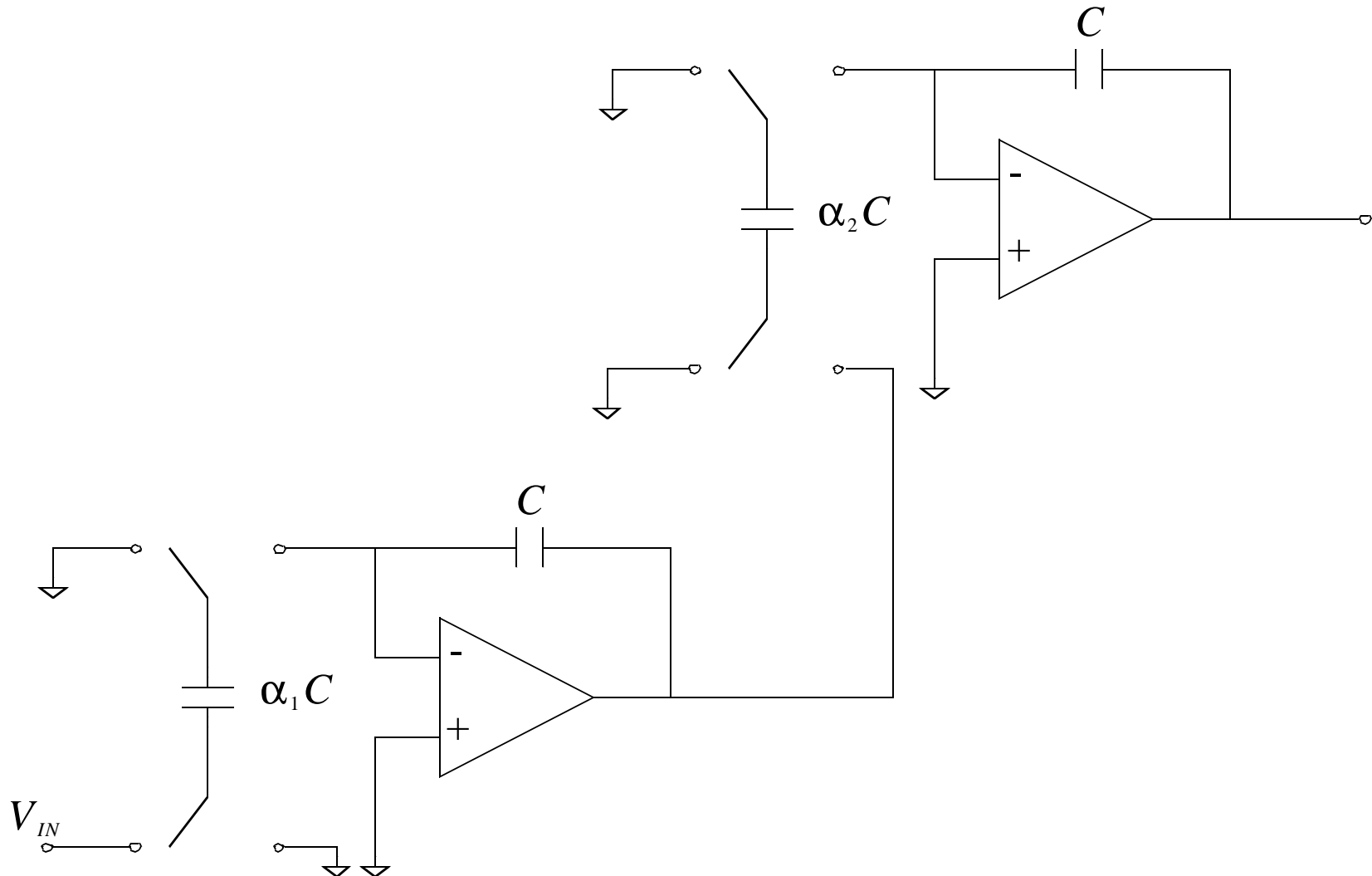
Requires control
of Ratios of C

S-C Integrator

APP-35

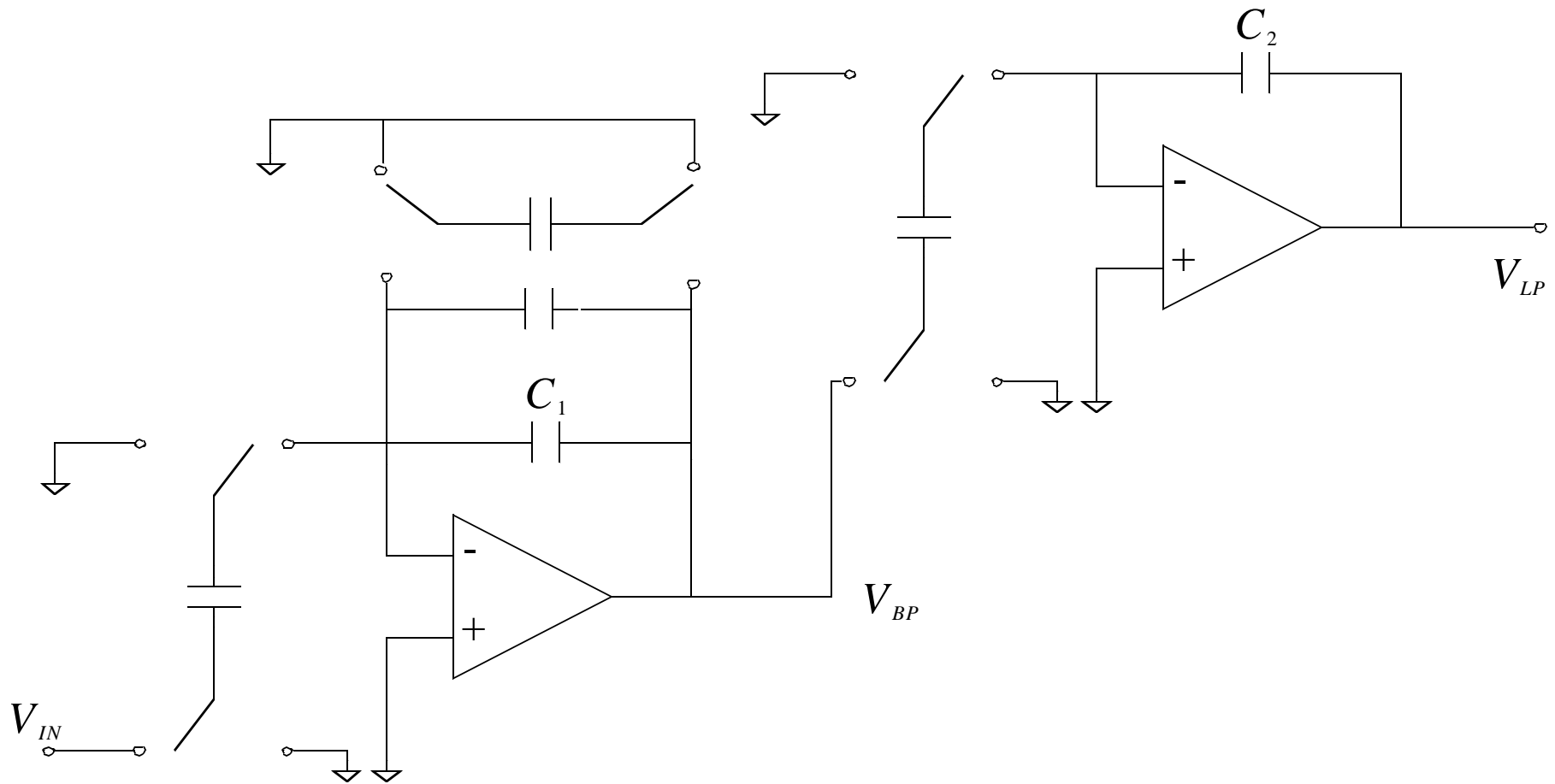


Two Integrators Together



Time Switched Equivalent Circuit

APP-37

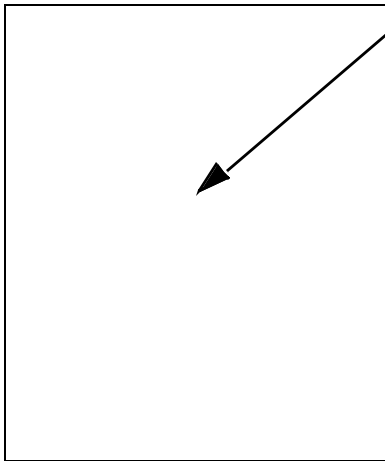


$$C_{ox} = \frac{\epsilon_{SiO_2}}{t_{ox}}$$

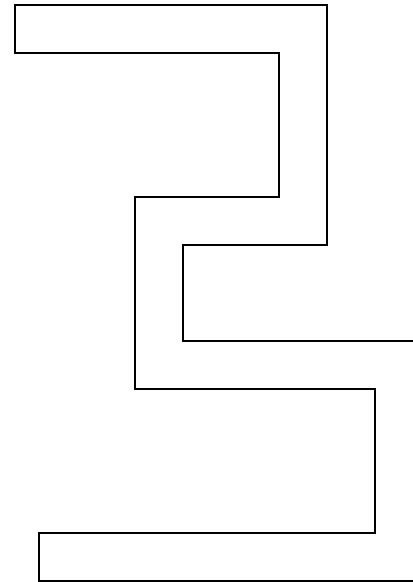
$$C_c = A_{cap} \cdot C_{ox}$$

$$R = \left(R \cdot \frac{\Omega}{\square} \right) \cdot (\# \square)$$

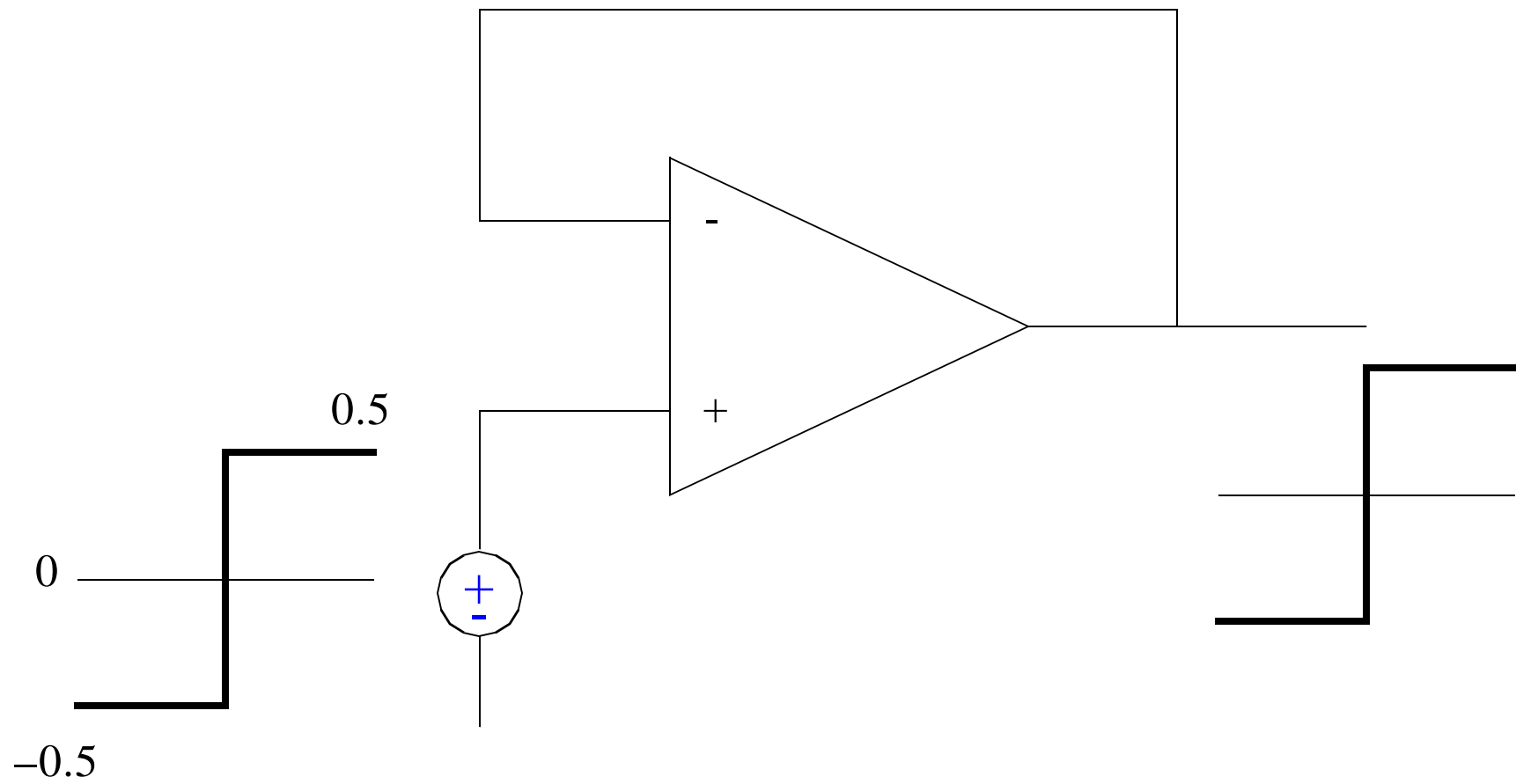
A_{cap}



□



APP-39



RF Front End

2.4GHz

800 – 900MHz

Crystal
Frequency Reference

Digital Radio

Front End

